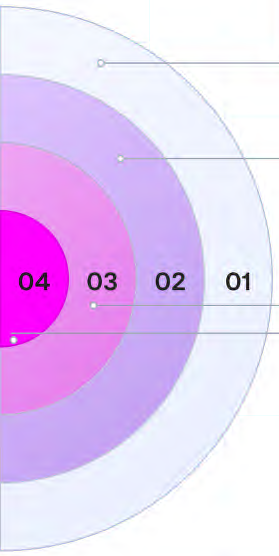
eventual

Signals. *At Scale*

Eventual is a YC-backed robotics data curation lab. We go beyond visual annotation with searchable scenarios, measurable signals, and enriched training data.
This is how we do it.



01 *Define Goals*

We start with the outcomes you want to improve in your robots or robotic model: task success rate, model accuracy, grasp reliability, or recovery from failures. With your researchers, we identify evaluation gaps and connect those metrics to the data you need.

02 *Generate Signals*

Custom pipelines trained for your task generate two kinds of signals. Researchers can "grep" for specific scenarios, such as a failed grasp of a deformable object followed by a successful retry, and compare measurable signals such as dexterity, novelty, and interesting physics to select useful training data.

03 *Verify Signals*

We compare interpretable signals against golden sets to assess their accuracy and timing. Alongside this validation, we enrich the data with hand-object contact regions, novel trajectories, interesting physics, and fine-grained subtask labels, etc., giving researchers richer ways to understand and select their training data.

04 *Deploy*

Eventual continuously enriches new data as it arrives and makes it available through our catalog APIs. Researchers, engineers, and agents can run automated research loops to select training data, train and evaluate models, and use evaluation gaps to guide the next round of enrichment.

See our Gallery @ eventual.ai/curation